

# LM4752

## Stereo 11W Audio Power Amplifier

### General Description

The LM4752 is a stereo audio amplifier capable of delivering 11W per channel of continuous average output power to a 4Ω load, or 7W per channel into 8Ω using a single 24V supply at 10% THD+N.

The LM4752 is specifically designed for single supply operation and a low external component count. The gain and bias resistors are integrated on chip, resulting in a 11W stereo amplifier in a compact 7 pin TO220 package. High output power levels at both 20V and 24V supplies and low external component count offer high value for compact stereo and TV applications. A simple mute function can be implemented with the addition of a few external components.

### Key Specifications

- Output power at 10% THD+N with 1kHz into 4Ω at  $V_{CC} = 24V$ : 11W (typ)
- Output power at 10% THD+N with 1kHz into 8Ω at  $V_{CC} = 24V$ : 7W (typ)
- Closed loop gain: 34dB (typ)
- $P_O$  at 10% THD+N @ 1 kHz into 4Ω single-ended TO-263 package at  $V_{CC} = 12V$ : 2.5W (typ)

- $P_O$  at 10% THD+N @ 1kHz into 8Ω bridged TO-263 package at  $V_{CC} = 12V$ : 5W (typ)

### Features

- Drives 4Ω and 8Ω loads
- Internal gain resistors ( $A_V = 34$  dB)
- Minimum external component requirement
- Single supply operation
- Internal current limiting
- Internal thermal protection
- Compact 7-lead TO-220 package
- Low cost-per-watt
- Wide supply range 9V - 40V

### Applications

- Compact stereos
- Stereo TVs
- Mini component stereos
- Multimedia speakers

### Typical Application

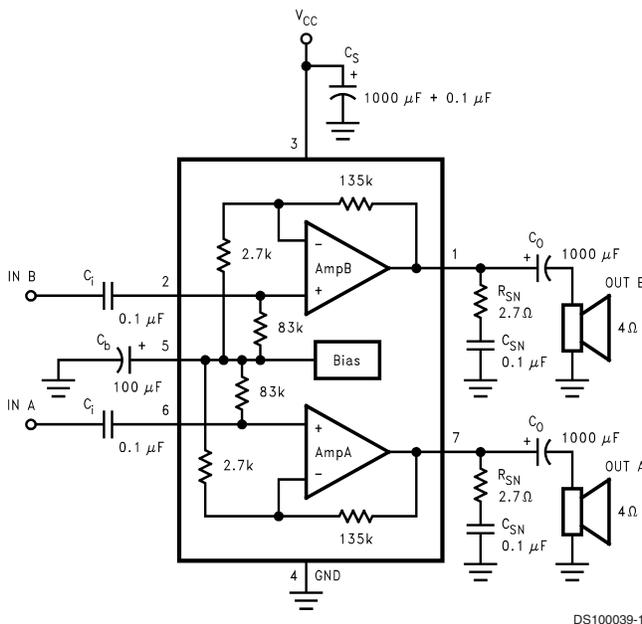
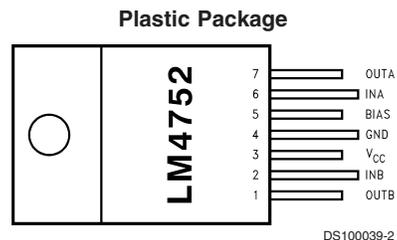
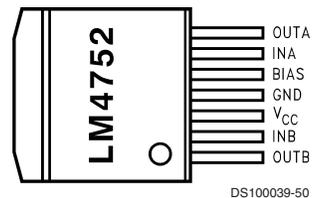


FIGURE 1. Typical Audio Amplifier Application Circuit

### Connection Diagram



Package Description  
Top View  
Order Number LM4752T  
Package Number TA07B



Package Description  
Top View  
Order Number LM4752TS  
Package Number TS07B

**Absolute Maximum Ratings** (Note 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage	40V
Input Voltage	±0.7V
Output Current	Internally Limited
Power Dissipation (Note 3)	62.5W
ESD Susceptibility (Note 4)	2 kV
Junction Temperature	150°C

Soldering Information	
T Package (10 sec)	250°C
Storage Temperature	-40°C to 150°C

**Operating Ratings**

Temperature Range	$T_{MIN} \leq T_A \leq T_{MAX}$	-40°C ≤ T <sub>A</sub> ≤ +85°C
Supply Voltage		9V to 32V
θ <sub>JC</sub>		2°C/W
θ <sub>JA</sub>		79°C/W

**Electrical Characteristics**

The following specifications apply to each channel with V<sub>CC</sub> = 24V, T<sub>A</sub> = 25°C unless otherwise specified.

Symbol	Parameter	Conditions	LM4752		Units (Limits)
			Typical (Note 5)	Limit (Note 6)	
I <sub>total</sub>	Total Quiescent Power Supply Current	V <sub>INAC</sub> = 0V, V <sub>o</sub> = 0V, R <sub>L</sub> = ∞	10.5	20 7	mA(max) mA(min)
P <sub>o</sub>	Output Power (Continuous Average per Channel)	f = 1 kHz, THD+N = 10%, R <sub>L</sub> = 8Ω f = 1 kHz, THD+N = 10%, R <sub>L</sub> = 4Ω V <sub>CC</sub> = 20V, R <sub>L</sub> = 8Ω V <sub>CC</sub> = 20V, R <sub>L</sub> = 4Ω f = 1 kHz, THD+N = 10%, R <sub>L</sub> = 4Ω V <sub>S</sub> = 12V, TO-263 Pkg.	7 4 7 2.5	10	W W(min) W W
THD+N	Total Harmonic Distortion plus Noise	f = 1 kHz, P <sub>o</sub> = 1 W/ch, R <sub>L</sub> = 8Ω	0.08		%
V <sub>OSW</sub>	Output Swing	R <sub>L</sub> = 8Ω, V <sub>CC</sub> = 20V R <sub>L</sub> = 4Ω, V <sub>CC</sub> = 20V	15 14		V V
X <sub>talk</sub>	Channel Separation	See Figure 1 f = 1 kHz, V <sub>o</sub> = 4 Vrms, R <sub>L</sub> = 8Ω	55		dB
PSRR	Power Supply Rejection Ratio	See Figure 1 V <sub>CC</sub> = 22V to 26V, R <sub>L</sub> = 8Ω	50		dB
V <sub>ODV</sub>	Differential DC Output Offset Voltage	V <sub>INAC</sub> = 0V	0.09	0.4	V(max)
SR	Slew Rate		2		V/μs
R <sub>IN</sub>	Input Impedance		83		kΩ
PBW	Power Bandwidth	3 dB BW at P <sub>o</sub> = 2.5W, R <sub>L</sub> = 8Ω	65		kHz
A <sub>VCL</sub>	Closed Loop Gain (Internally Set)	R <sub>L</sub> = 8Ω	34	33 35	dB(min) dB(max)
e <sub>in</sub>	Noise	IHF-A Weighting Filter, R <sub>L</sub> = 8Ω Output Referred	0.2		mVrms
I <sub>o</sub>	Output Short Circuit Current Limit	V <sub>IN</sub> = 0.5V, R <sub>L</sub> = 2Ω		2	A(min)

**Note 1:** All voltages are measured with respect to the GND pin (4), unless otherwise specified.

**Note 2:** *Absolute Maximum Ratings* indicate limits beyond which damage to the device may occur. *Operating Ratings* indicate conditions for which the device is functional, but do not guarantee specific performance limits. *Electrical Characteristics* state DC and AC electrical specifications under particular test conditions which guarantee specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not guaranteed for parameters where no limit is given, however, the typical value is a good indication of device performance.

**Note 3:** For operating at case temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of θ<sub>JC</sub> = 2°C/W (junction to case). Refer to the section Determining the Maximum Power Dissipation in the **Application Information** section for more information.

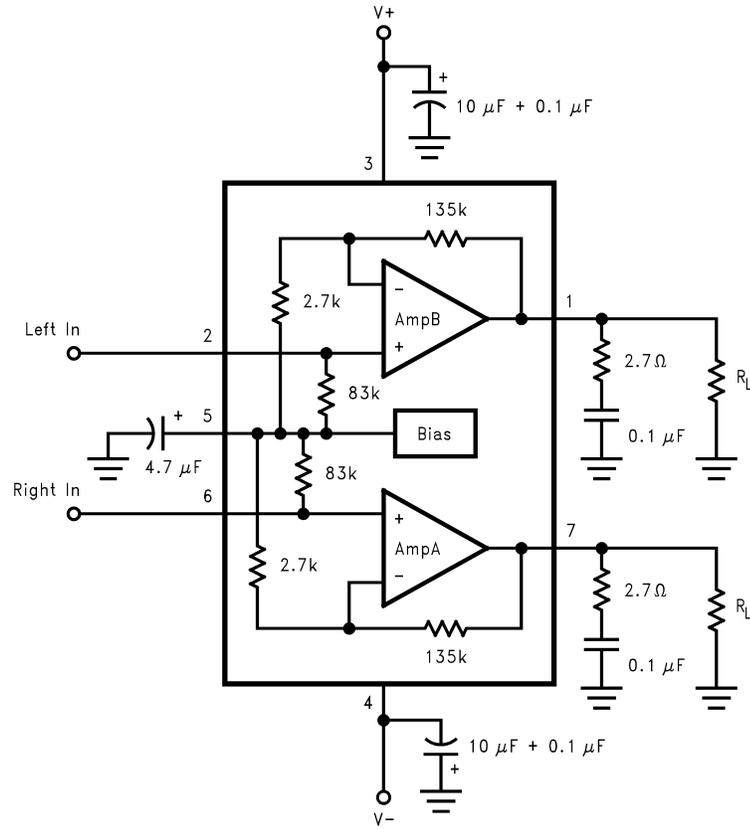
**Note 4:** Human body model, 100 pF discharged through a 1.5 kΩ resistor.

**Note 5:** Typicals are measured at 25°C and represent the parametric norm.

**Note 6:** Limits are guarantees that all parts are tested in production to meet the stated values.

**Note 7:** The TO-263 Package is not recommended for V<sub>S</sub> > 16V due to impractical heatsinking limitations.

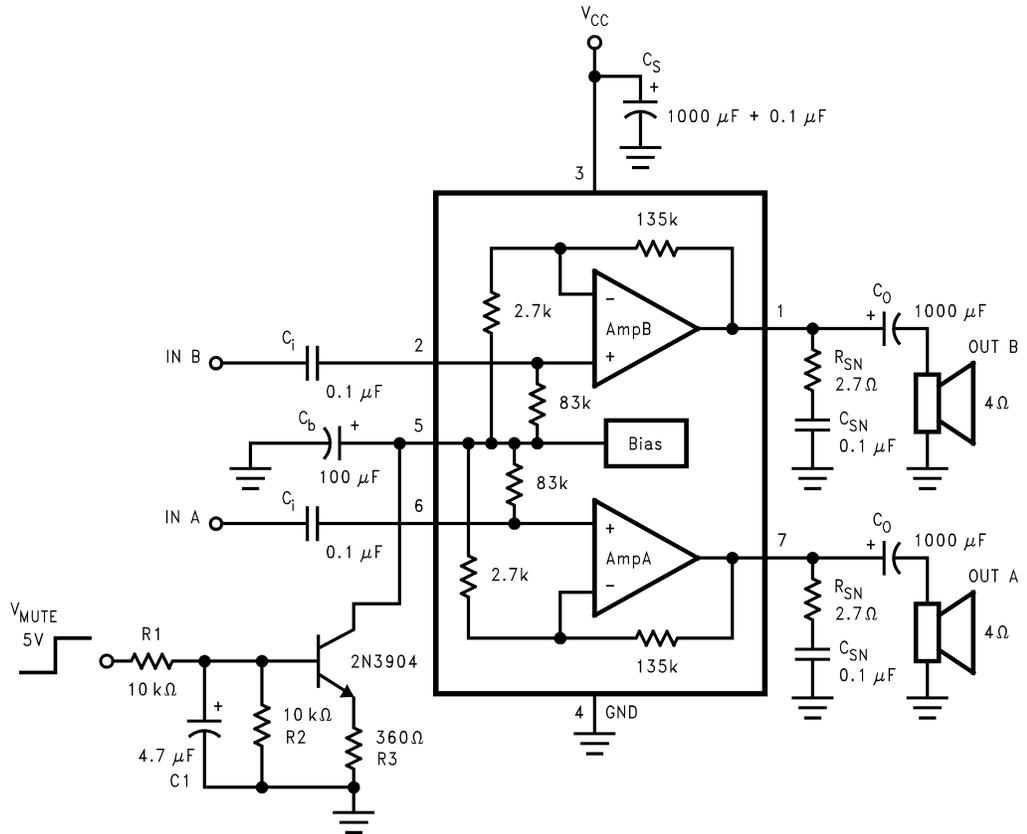
Test Circuit



DS100039-36

FIGURE 2. Test Circuit

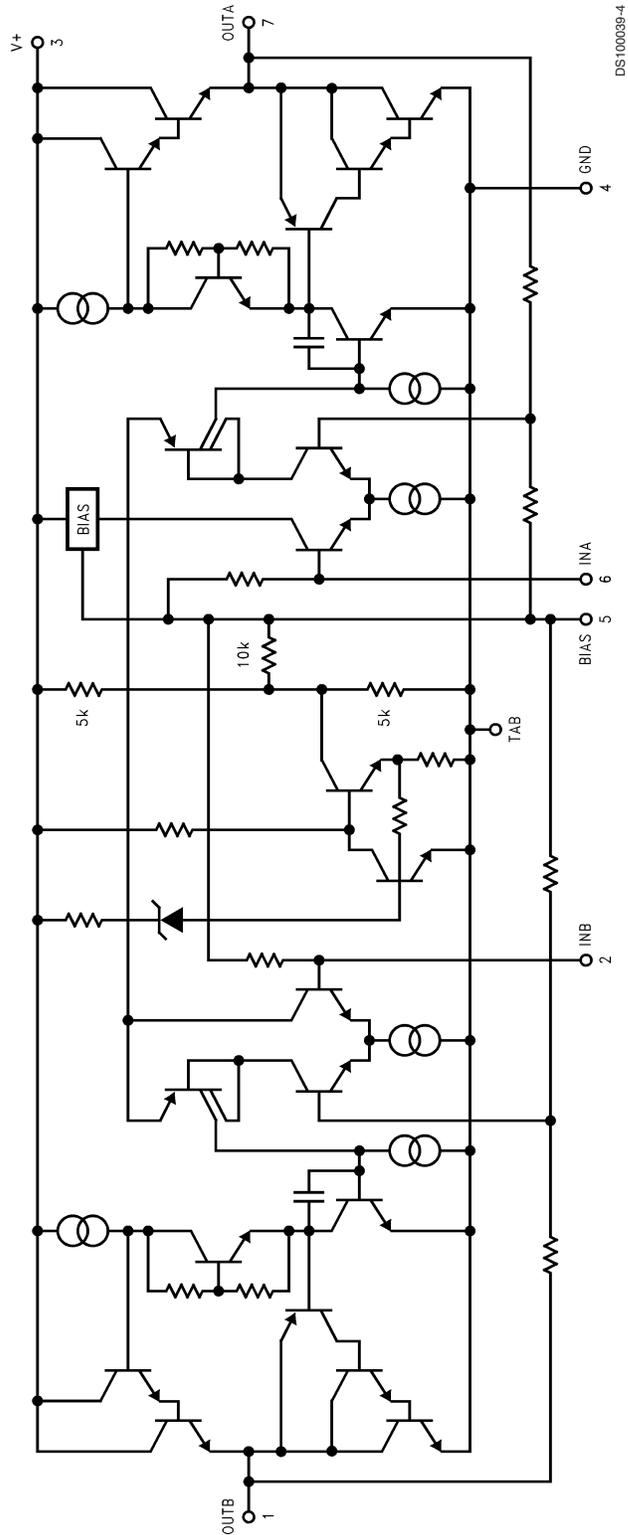
### Typical Application with Mute



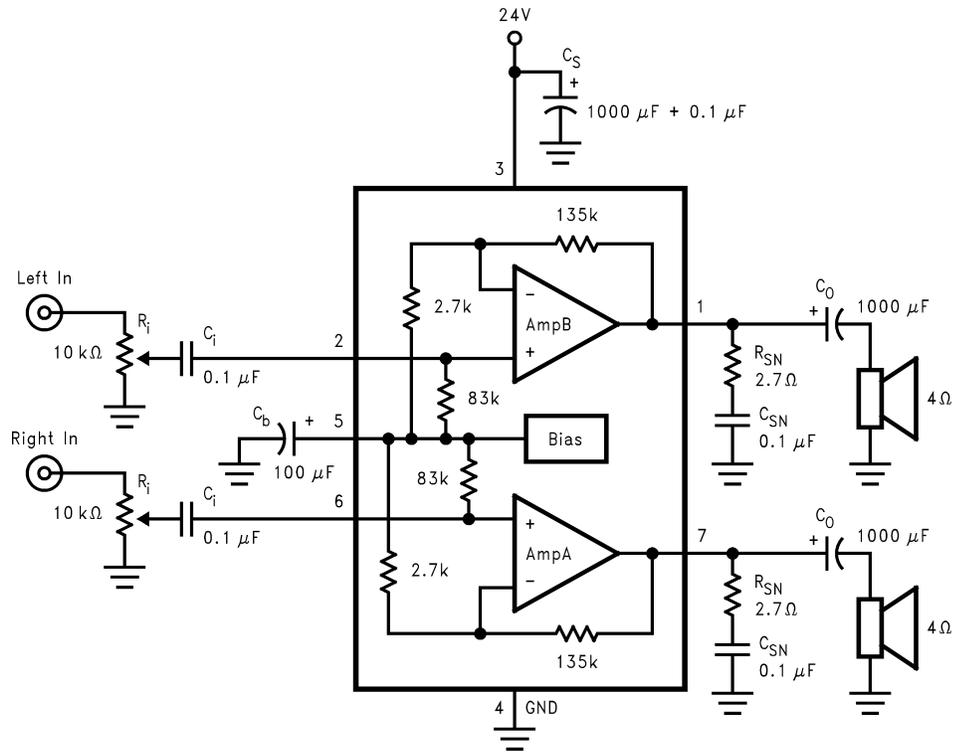
DS100039-3

FIGURE 3. Application with Mute Function

# Equivalent Schematic Diagram



## System Application Circuit



DS100039-5

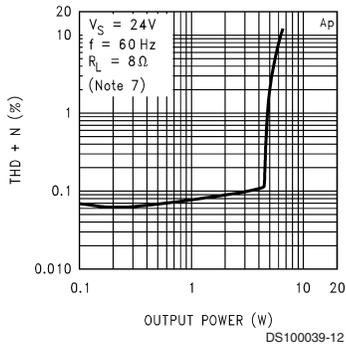
FIGURE 4. Circuit for External Components Description

### External Components Description

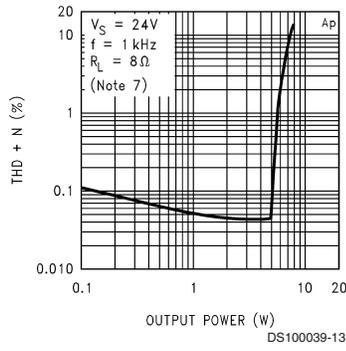
Components	Function Description
1, 2 Cs	Provides power supply filtering and bypassing.
3, 4 Rsn	Works with Csn to stabilize the output stage from high frequency oscillations.
5, 6 Csn	Works with Rsn to stabilize the output stage from high frequency oscillations.
7 Cb	Provides filtering for the internally generated half-supply bias generator.
8, 9 Ci	Input AC coupling capacitor which blocks DC voltage at the amplifier's input terminals. Also creates a high pass filter with $f_c=1/(2 \cdot \pi \cdot R_{in} \cdot C_{in})$ .
10, 11 Co	Output AC coupling capacitor which blocks DC voltage at the amplifier's output terminal. Creates a high pass filter with $f_c=1/(2 \cdot \pi \cdot R_{out} \cdot C_{out})$ .
12, 13 Ri	Voltage control - limits the voltage level to the amplifier's input terminals.

# Typical Performance Characteristics

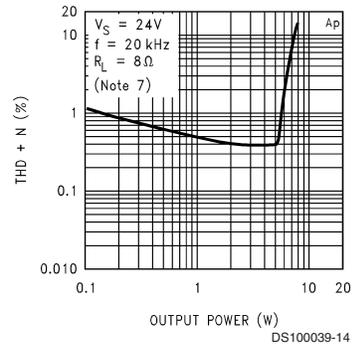
THD+N vs Output Power



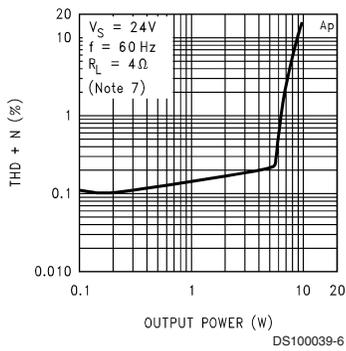
THD+N vs Output Power



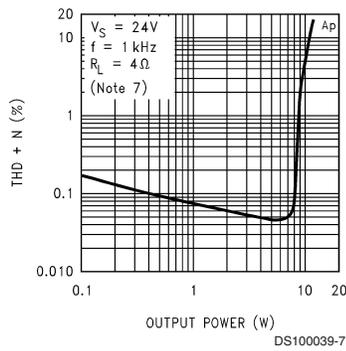
THD+N vs Output Power



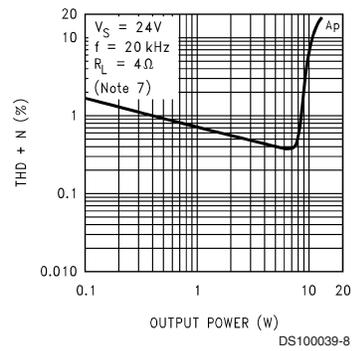
THD+N vs Output Power



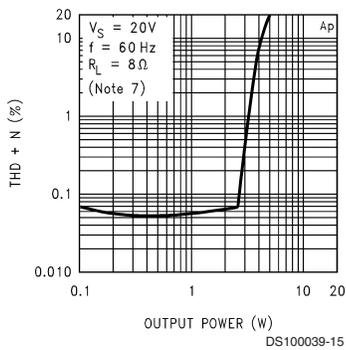
THD+N vs Output Power



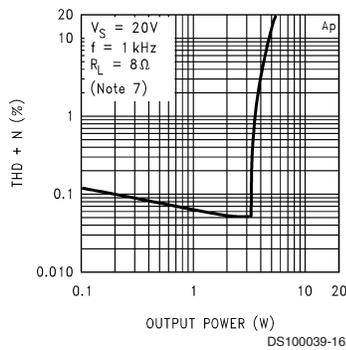
THD+N vs Output Power



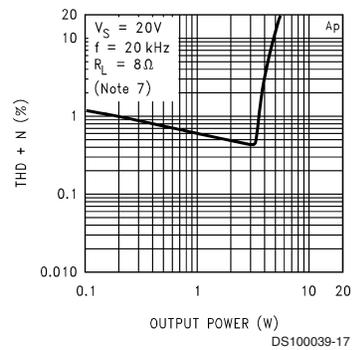
THD+N vs Output Power



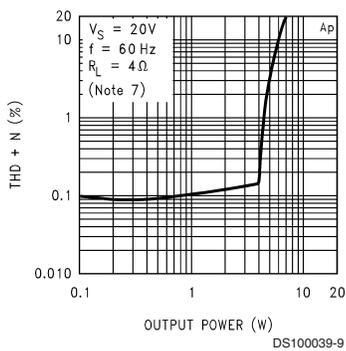
THD+N vs Output Power



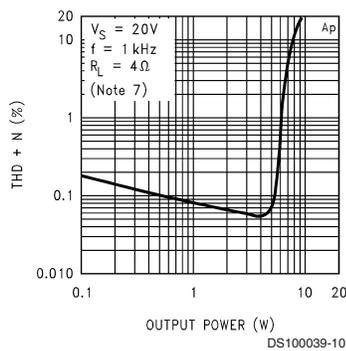
THD+N vs Output Power



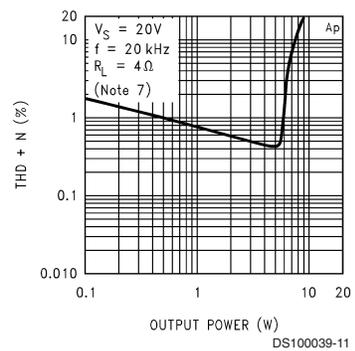
THD+N vs Output Power



THD+N vs Output Power

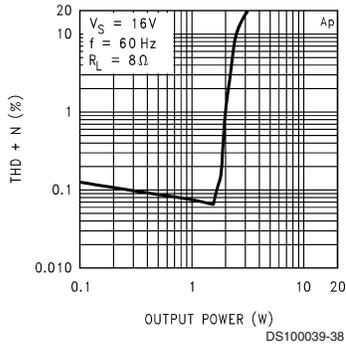


THD+N vs Output Power

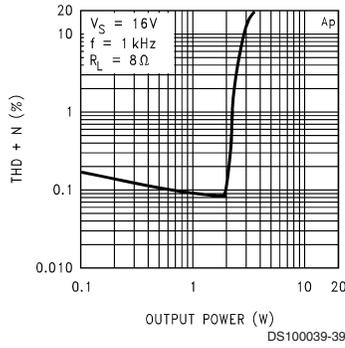


# Typical Performance Characteristics (Continued)

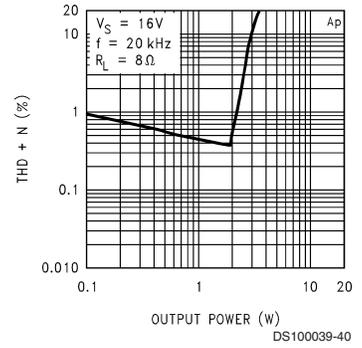
THD+N vs Output Power



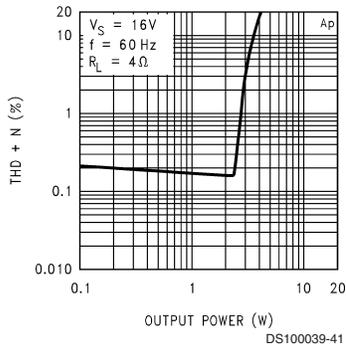
THD+N vs Output Power



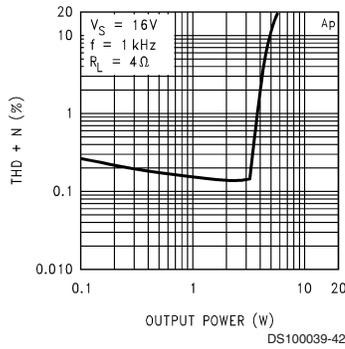
THD+N vs Output Power



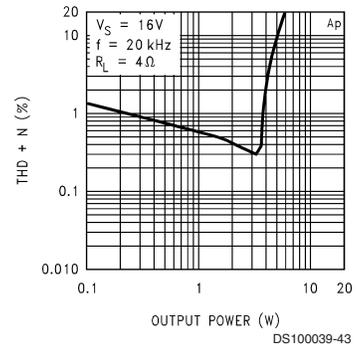
THD+N vs Output Power



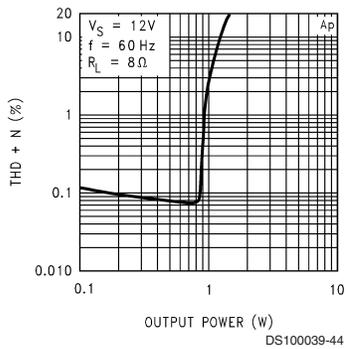
THD+N vs Output Power



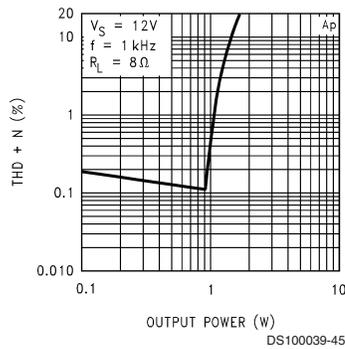
THD+N vs Output Power



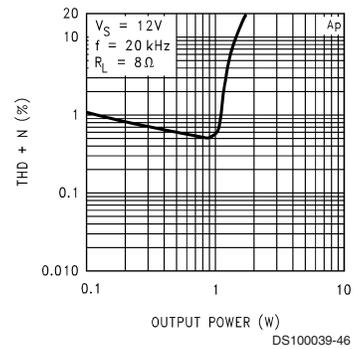
THD+N vs Output Power



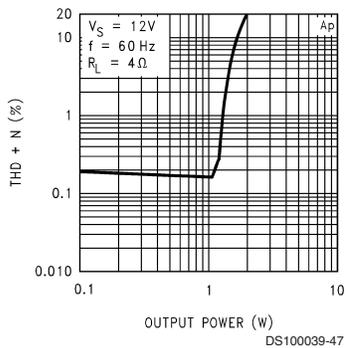
THD+N vs Output Power



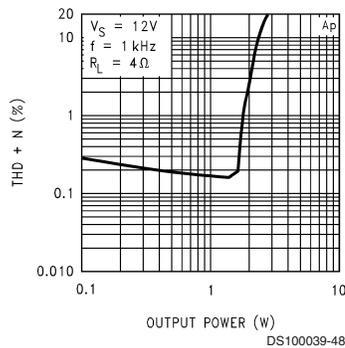
THD+N vs Output Power



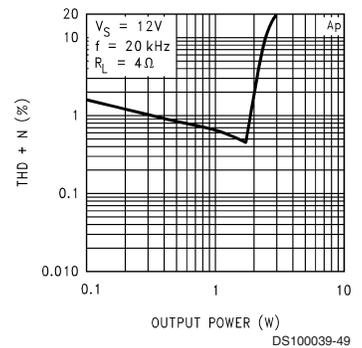
THD+N vs Output Power



THD+N vs Output Power

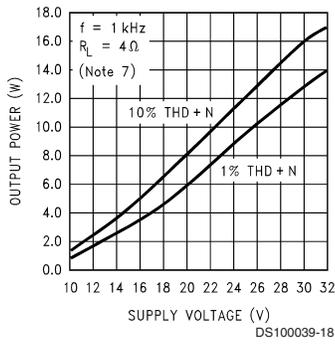


THD+N vs Output Power

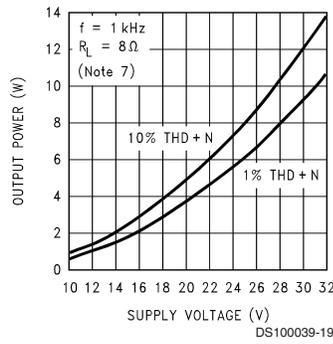


# Typical Performance Characteristics (Continued)

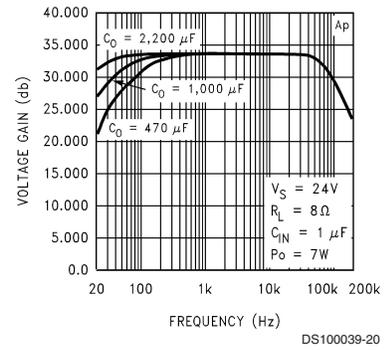
**Output Power vs Supply Voltage**



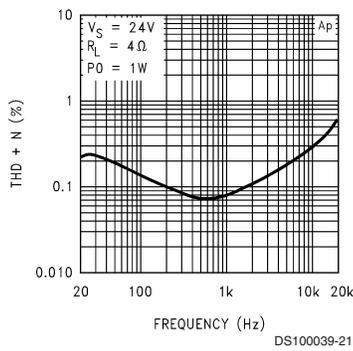
**Output Power vs Supply Voltage**



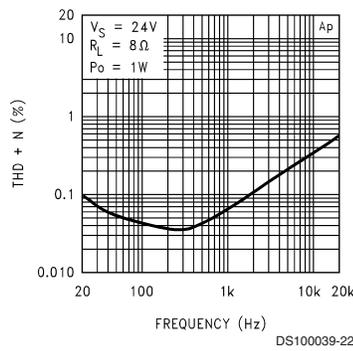
**Frequency Response**



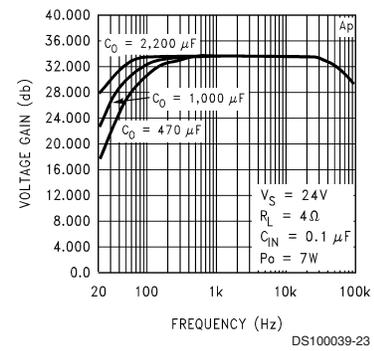
**THD+N vs Frequency**



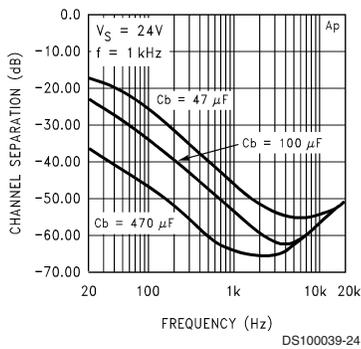
**THD+N vs Frequency**



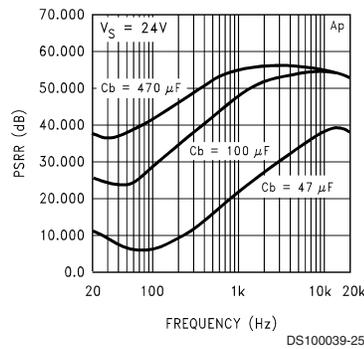
**Frequency Response**



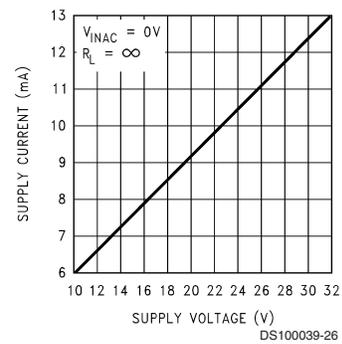
**Channel Separation**



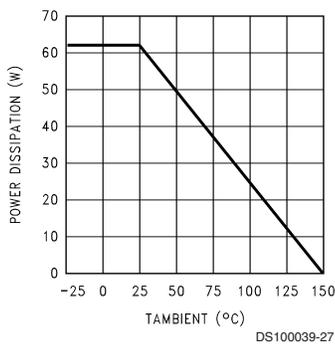
**PSRR vs Frequency**



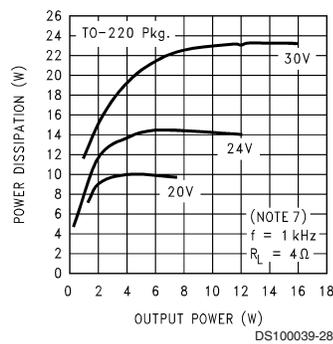
**Supply Current vs Supply Voltage**



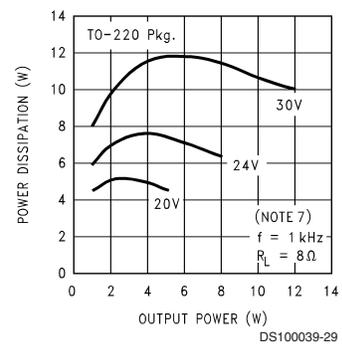
**Power Derating Curve**



**Power Dissipation vs Output Power**

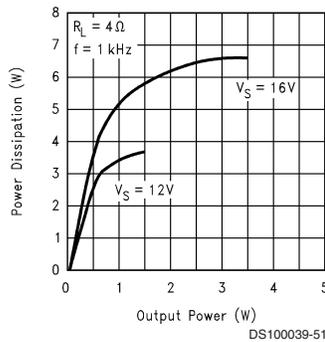


**Power Dissipation vs Output Power**

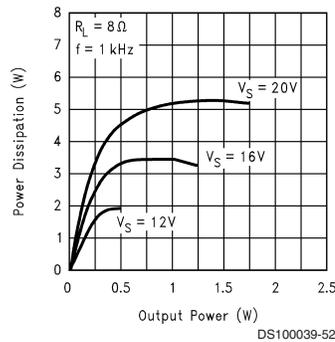


## Typical Performance Characteristics (Continued)

Power Dissipation vs Output Power



Power Dissipation vs Output Power



## Application Information

### CAPACITOR SELECTION AND FREQUENCY RESPONSE

With the LM4752, as in all single supply amplifiers, AC coupling capacitors are used to isolate the DC voltage present at the inputs (pins 2,6) and outputs (pins 1,7). As mentioned earlier in the **External Components** section these capacitors create high-pass filters with their corresponding input/output impedances. The **Typical Application Circuit** shown in *Figure 1* shows input and output capacitors of 0.1  $\mu\text{F}$  and 1,000  $\mu\text{F}$  respectively. At the input, with an 83 k $\Omega$  typical input resistance, the result is a high pass 3 dB point occurring at 19 Hz. There is another high pass filter at 39.8 Hz created with the output load resistance of 4 $\Omega$ . Careful selection of these components is necessary to ensure that the desired frequency response is obtained. The Frequency Response curves in the **Typical Performance Characteristics** section show how different output coupling capacitors affect the low frequency rolloff.

### APPLICATION CIRCUIT WITH MUTE

With the addition of a few external components, a simple mute circuit can be implemented, such as the one shown in *Figure 3*. This circuit works by externally pulling down the half supply bias line (pin 5), effectively shutting down the input stage.

When using an external circuit to pull down the bias, care must be taken to ensure that this line is not pulled down too quickly, or output “pops” or signal feedthrough may result. If the bias line is pulled down too quickly, currents induced in the internal bias resistors will cause a momentary DC voltage to appear across the inputs of each amplifier’s internal

differential pair, resulting in an output DC shift towards  $V_{\text{SUPPLY}}$ . An R-C timing circuit should be used to limit the pull-down time such that output “pops” and signal feedthroughs will be minimized. The pull-down timing is a function of a number of factors, including the external mute circuitry, the voltage used to activate the mute, the bias capacitor, the half-supply voltage, and internal resistances used in the half-supply generator. *Table 1* shows a list of recommended values for the external mute circuitry.

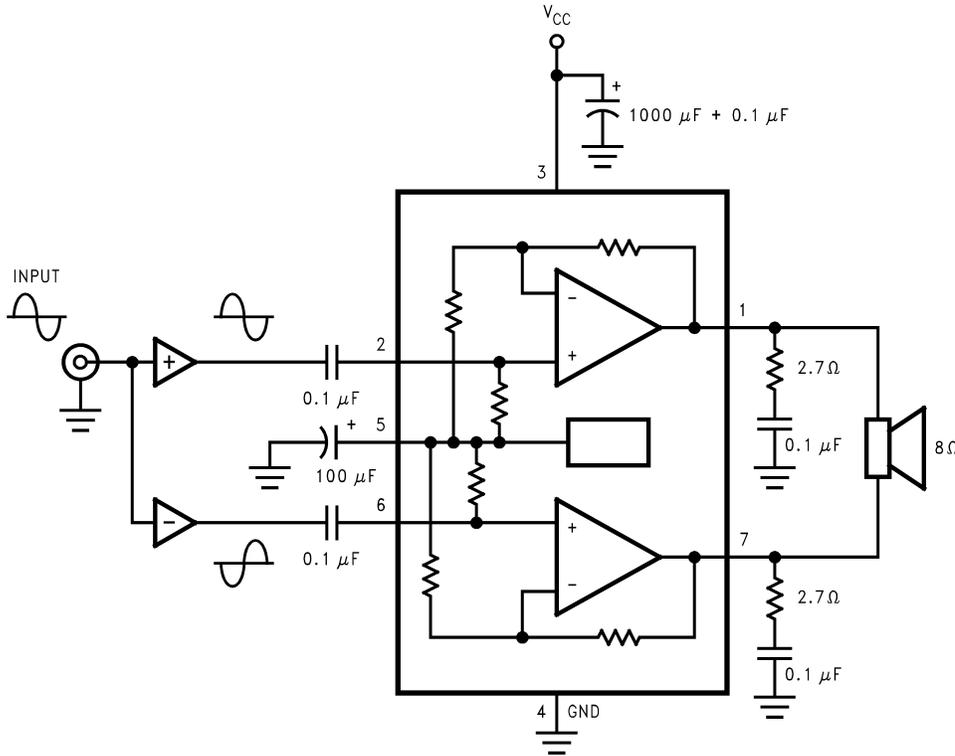
TABLE 1. Values for Mute Circuit

$V_{\text{MUTE}}$	R1	R2	C1	R3	$C_{\text{B}}$	$V_{\text{CC}}$
5V	10 k $\Omega$	10 k $\Omega$	4.7 $\mu\text{F}$	360 $\Omega$	100 $\mu\text{F}$	21V–32V
$V_{\text{S}}$	20 k $\Omega$	1.2 k $\Omega$	4.7 $\mu\text{F}$	180 $\Omega$	100 $\mu\text{F}$	15V–32V
$V_{\text{S}}$	20 k $\Omega$	910 $\Omega$	4.7 $\mu\text{F}$	180 $\Omega$	47 $\mu\text{F}$	22V–32V

### OPERATING IN BRIDGE-MODE

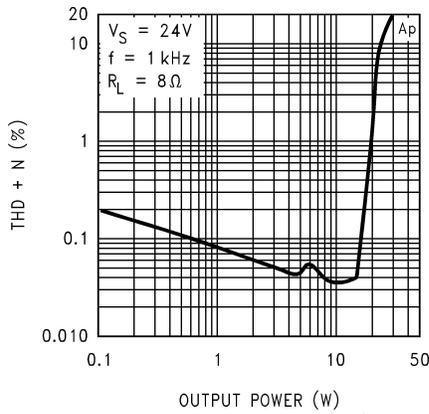
Though designed for use as a single-ended amplifier, the LM4752 can be used to drive a load differentially (bridge-mode). Due to the low pin count of the package, only the non-inverting inputs are available. An inverted signal must be provided to one of the inputs. This can easily be done with the use of an inexpensive op-amp configured as a standard inverting amplifier. An LF353 is a good low-cost choice. Care must be taken, however, for a bridge-mode amplifier must theoretically dissipate four times the power of a single-ended type. The load seen by each amplifier is effectively half that of the actual load being used, thus an amplifier designed to drive a 4 $\Omega$  load in single-ended mode should drive an 8 $\Omega$  load when operating in bridge-mode.

Application Information (Continued)

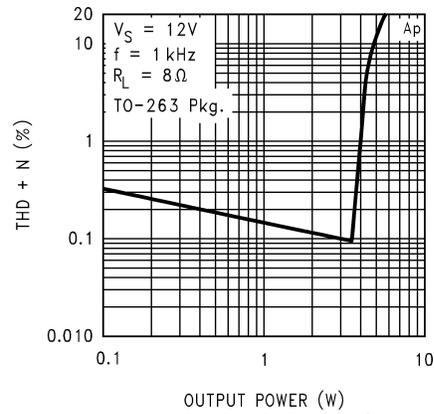


DS100039-30

FIGURE 5. Bridge-Mode Application



DS100039-31



DS100039-37

FIGURE 6. THD+N vs. P<sub>OUT</sub> for Bridge-Mode Application

PREVENTING OSCILLATIONS

With the integration of the feedback and bias resistors on-chip, the LM4752 fits into a very compact package. However, due to the close proximity of the non-inverting input pins to the corresponding output pins, the inputs should be AC terminated at all times. If the inputs are left floating, the amplifier will have a positive feedback path through high impedance coupling, resulting in a high frequency oscillation. In most applications, this termination is typically provided by the previous stage's source impedance. If the application will require an external signal, the inputs should be terminated to ground with a resistance of 50 kΩ or less on the AC side of the input coupling capacitors.

UNDERVOLTAGE SHUTDOWN

If the power supply voltage drops below the minimum operating supply voltage, the internal under-voltage detection circuitry pulls down the half-supply bias line, shutting down the preamp section of the LM4752. Due to the wide operating supply range of the LM4752, the threshold is set to just under 9V. There may be certain applications where a higher threshold voltage is desired. One example is a design requiring a high operating supply voltage, with large supply and bias capacitors, and there is little or no other circuitry connected to the main power supply rail. In this circuit, when the power is disconnected, the supply and bias capacitors will discharge at a slower rate, possibly resulting in audible output distortion as the decaying voltage begins to clip the

## Application Information (Continued)

output signal. An external circuit may be used to sense for the desired threshold, and pull the bias line (pin5) to ground to disable the input preamp. Figure 7 shows an example of such a circuit. When the voltage across the zener diode drops below its threshold, current flow into the base of Q1 is interrupted. Q2 then turns on, discharging the bias capacitor. This discharge rate is governed by several factors, including the bias capacitor value, the bias voltage, and the resistor at the emitter of Q2. An equation for approximating the value of the emitter discharge resistor, R, is given below:

$$R = (0.7V) / (C_B \cdot (V_S / 2) / 0.1s)$$

Note that this is only a linearized approximation based on a discharge time of 0.1s. The circuit should be evaluated and adjusted for each application.

As mentioned earlier in the **Application Circuit with Mute** section, when using an external circuit to pull down the bias line, the rate of discharge will have an effect on the turn-off induced distortions. Please refer to the **Application Circuit with Mute** section for more information.

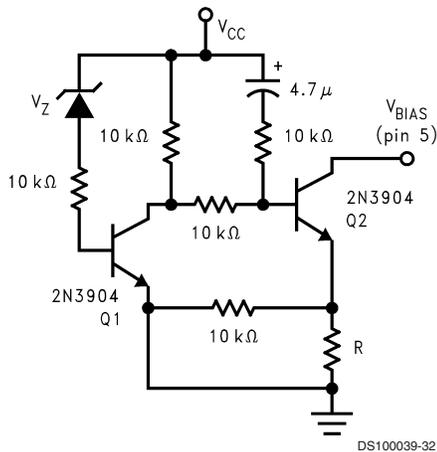


FIGURE 7. External Undervoltage Pull-Down

### THERMAL CONSIDERATIONS

#### Heat Sinking

Proper heatsinking is necessary to ensure that the amplifier will function correctly under all operating conditions. A heat-sink that is too small will cause the die to heat excessively and will result in a degraded output signal as the internal thermal protection circuitry begins to operate.

The choice of a heatsink for a given application is dictated by several factors: the maximum power the IC needs to dissipate, the worst-case ambient temperature of the circuit, the junction-to-case thermal resistance, and the maximum junction temperature of the IC. The heat flow approximation equation used in determining the correct heatsink maximum thermal resistance is given below:

$$T_J - T_A = P_{DMAX} \cdot (\theta_{JC} + \theta_{CS} + \theta_{SA})$$

where:

$P_{DMAX}$  = maximum power dissipation of the IC

$T_J$  (°C) = junction temperature of the IC

$T_A$  (°C) = ambient temperature

$\theta_{JC}$  (°C/W) = junction-to-case thermal resistance of the IC

$\theta_{CS}$  (°C/W) = case-to-heatsink thermal resistance (typically 0.2 to 0.5 °C/W)

$\theta_{SA}$  (°C/W) = thermal resistance of heatsink

When determining the proper heatsink, the above equation should be re-written as:

$$\theta_{SA} \leq [(T_J - T_A) / P_{DMAX}] - \theta_{JC} - \theta_{CS}$$

### TO-263 HEATSINKING

Surface mount applications will be limited by the thermal dissipation properties of printed circuit board area. The TO-263 package is not recommended for surface mount applications with  $V_S > 16V$  due to limited printed circuit board area. There are TO-263 package enhancements, such as clip-on heatsinks and heatsinks with adhesives, that can be used to improve performance.

Standard FR-4 single-sided copper clad will have an approximate Thermal resistance ( $\theta_{SA}$ ) ranging from:

1.5 x 1.5 in. sq.	20–27°C/W	( $T_A=28^\circ\text{C}$ , Sine wave testing, 1 oz. Copper)
2 x 2 in. sq.	16–23°C/W	

The above values for  $\theta_{SA}$  vary widely due to dimensional proportions (i.e. variations in width and length will vary  $\theta_{SA}$ ).

For audio applications, where peak power levels are short in duration, this part will perform satisfactory with less heatsinking/copper clad area. As with any high power design proper bench testing should be undertaken to assure the design can dissipate the required power. Proper bench testing requires attention to worst case ambient temperature and air flow. At high power dissipation levels the part will show a tendency to increase saturation voltages, thus limiting the undistorted power levels.

### Determining Maximum Power Dissipation

For a single-ended class AB power amplifier, the theoretical maximum power dissipation point is a function of the supply voltage,  $V_S$ , and the load resistance,  $R_L$  and is given by the following equation:

(single channel)

$$P_{DMAX} (W) = [V_S^2 / (2 \cdot \pi^2 \cdot R_L)]$$

The above equation is for a single channel class-AB power amplifier. For dual amplifiers such as the LM4752, the equation for calculating the total maximum power dissipated is:

(dual channel)

$$P_{DMAX} (W) = 2 \cdot [V_S^2 / (2 \cdot \pi^2 \cdot R_L)]$$

or

$$V_S^2 / (\pi^2 \cdot R_L)$$

(Bridged Outputs)

$$P_{DMAX} (W) = 4[V_S^2 / (2\pi^2 \cdot R_L)]$$

### Heatsink Design Example:

Determine the system parameters:

$V_S = 24V$  Operating Supply Voltage

$R_L = 4\Omega$  Minimum load impedance

$T_A = 55^\circ\text{C}$  Worst case ambient temperature

Device parameters from the datasheet:

$T_J = 150^\circ\text{C}$  Maximum junction temperature

$\theta_{JC} = 2^\circ\text{C/W}$  Junction-to-case thermal resistance

Calculations:

$$2 \cdot P_{DMAX} = 2 \cdot [V_S^2 / (2 \cdot \pi^2 \cdot R_L)] = (24V)^2 / (2 \cdot \pi^2 \cdot 4\Omega) = 14.6W$$

$$\theta_{SA} \leq [(T_J - T_A) / P_{DMAX}] - \theta_{JC} - \theta_{CS} = [(150^\circ\text{C} - 55^\circ\text{C}) / 14.6W] - 2^\circ\text{C/W} - 0.2^\circ\text{C/W} = 4.3^\circ\text{C/W}$$

Conclusion: Choose a heatsink with  $\theta_{SA} \leq 4.3^\circ\text{C/W}$ .

## Application Information (Continued)

### TO-263 HEATSINK DESIGN EXAMPLES:

Example 1: (Stereo Single-Ended Output)

Given:  $T_A=30^\circ\text{C}$   
 $T_J=150^\circ\text{C}$   
 $R_L=4\Omega$   
 $V_S=12\text{V}$   
 $\theta_{JC}=2^\circ\text{C/W}$

$P_{D\text{MAX}}$  from  $P_D$  vs  $P_O$  Graph:

$$P_{D\text{MAX}} \approx 3.7\text{W}$$

Calculating  $P_{D\text{MAX}}$ :

$$P_{D\text{MAX}} = V_{CC}^2 / (\pi^2 R_L) = (12\text{V})^2 / (\pi^2(4\Omega)) = 3.65\text{W}$$

Calculating Heatsink Thermal Resistance:

$$\theta_{SA} < [(T_J - T_A) / P_{D\text{MAX}}] - \theta_{JC} - \theta_{CS}$$

$$\theta_{SA} < 120^\circ\text{C} / 3.7\text{W} - 2.0^\circ\text{C/W} - 0.2^\circ\text{C/W} = 30.2^\circ\text{C/W}$$

Therefore the recommendation is to use 1.5 x 1.5 square inch of single-sided copper clad.

Example 2: (Stereo Single-Ended Output)

Given:  $T_A=50^\circ\text{C}$   
 $T_J=150^\circ\text{C}$   
 $R_L=4\Omega$   
 $V_S=12\text{V}$   
 $\theta_{JC}=2^\circ\text{C/W}$

$P_{D\text{MAX}}$  from  $P_D$  vs  $P_O$  Graph:

$$P_{D\text{MAX}} \approx 3.7\text{W}$$

Calculating  $P_{D\text{MAX}}$ :

$$P_{D\text{MAX}} = V_{CC}^2 / (\pi^2 R_L) = (12\text{V})^2 / (\pi^2(4\Omega)) = 3.65\text{W}$$

Calculating Heatsink Thermal Resistance:

$$\theta_{SA} < [(T_J - T_A) / P_{D\text{MAX}}] - \theta_{JC} - \theta_{CS}$$

$$\theta_{SA} < 100^\circ\text{C} / 3.7\text{W} - 2.0^\circ\text{C/W} - 0.2^\circ\text{C/W} = 24.8^\circ\text{C/W}$$

Therefore the recommendation is to use 2.0 x 2.0 square inch of single-sided copper clad.

Example 3: (Bridged Output)

Given:  $T_A=50^\circ\text{C}$   
 $T_J=150^\circ\text{C}$   
 $R_L=8\Omega$   
 $V_S=12\text{V}$   
 $\theta_{JC}=2^\circ\text{C/W}$

Calculating  $P_{D\text{MAX}}$ :

$$P_{D\text{MAX}} = 4[V_{CC}^2 / (2\pi^2 R_L)] = 4(12\text{V})^2 / (2\pi^2(8\Omega)) = 3.65\text{W}$$

Calculating Heatsink Thermal Resistance:

$$\theta_{SA} < [(T_J - T_A) / P_{D\text{MAX}}] - \theta_{JC} - \theta_{CS}$$

$$\theta_{SA} < 100^\circ\text{C} / 3.7\text{W} - 2.0^\circ\text{C/W} - 0.2^\circ\text{C/W} = 24.8^\circ\text{C/W}$$

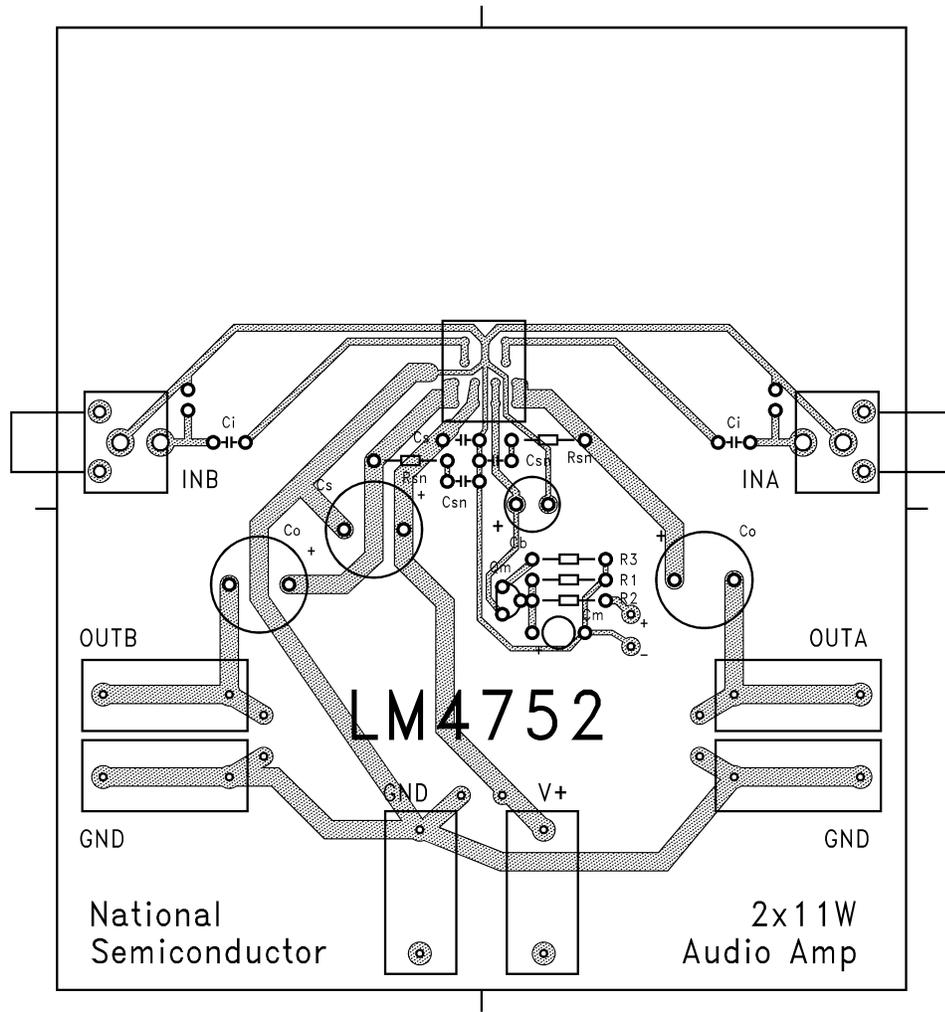
Therefore the recommendation is to use 2.0 x 2.0 square inch of single-sided copper clad.

### Layout and Ground Returns

Proper PC board layout is essential for good circuit performance. When laying out a PC board for an audio power amplifier, particular attention must be paid to the routing of the output signal ground returns relative to the input signal and bias capacitor grounds. To prevent any ground loops, the ground returns for the output signals should be routed separately and brought together at the supply ground. The input signal grounds and the bias capacitor ground line should also be routed separately. The 0.1  $\mu\text{F}$  high frequency supply bypass capacitor should be placed as close as possible to the IC.

**Application Information** (Continued)

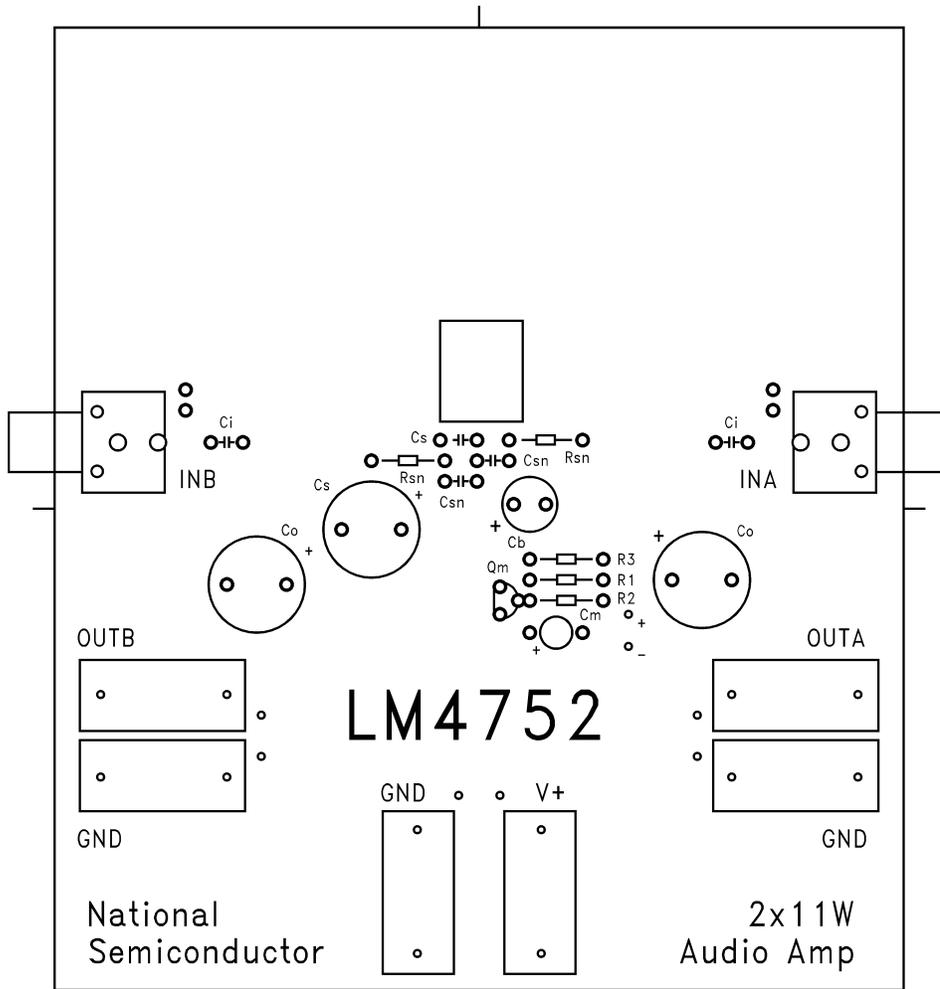
**PC BOARD LAYOUT—COMPOSITE**



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# Application Information (Continued)

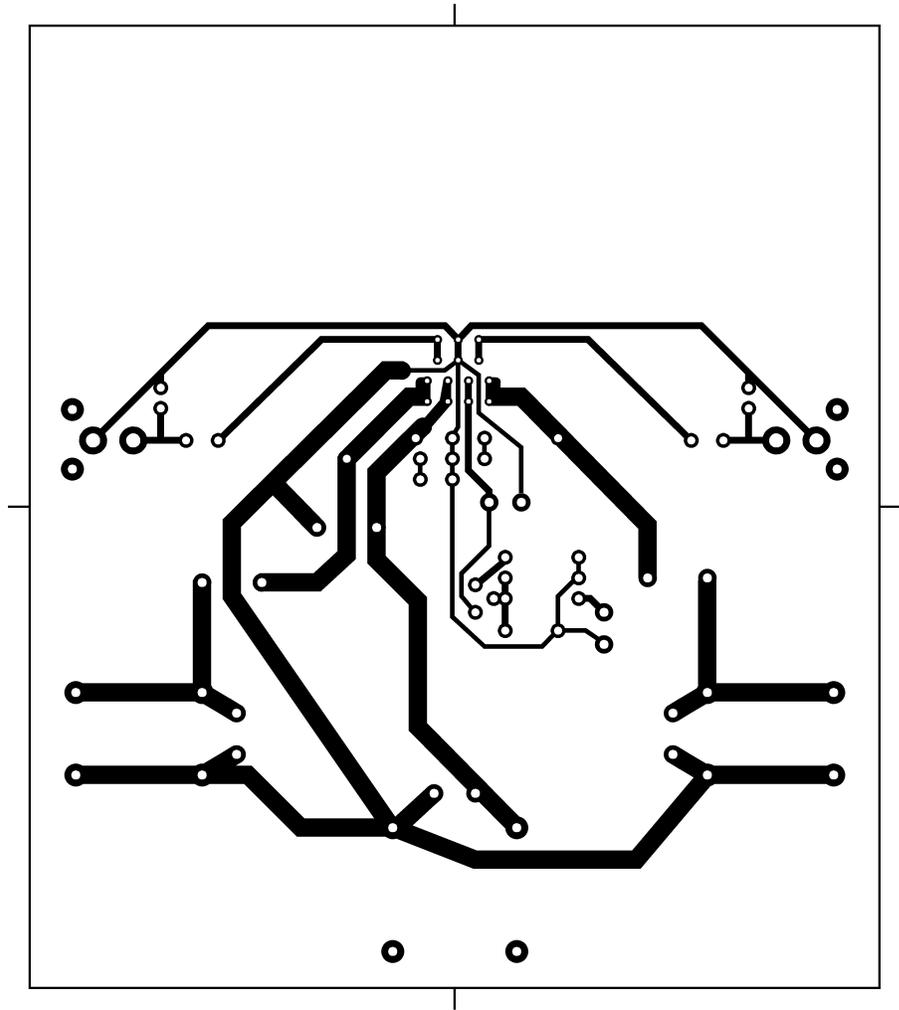
## PC BOARD LAYOUT—SILK SCREEN



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# Application Information (Continued)

## PC BOARD LAYOUT—SOLDER SIDE



DS100039-35



## Notes

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